

AMENDMENTS TO THE SPECIFICATION:

Please delete the paragraph beginning on page 1, line 21 and ending on page 2, line 5 and replace with the following:

B1
In this case, although the distance to the main object to be focused is determined from [[the]] measurement information, the measurement data are not necessarily measurement data having high reliability. For example, United States Patent Application No. 5,068,737 discloses art which accomplishes focus adjustment using data having high reliability as a method of focus adjustment in these cases. In addition, Japanese Laid-Open Patent Application No. 11-119088 discloses a focus adjustment method for focusing when data reliability is low.

Please delete the paragraph beginning on page 17, line 1 and ending on page 17, line 13 and replace with the following:

B2
First, the data processing circuit 100 reads the output data of the sensor 114 from the distance measuring module 110 (#10), and executes the distance measuring calculation for a specific number N of measuring points (#12). Then, the distance data D(i) is calculated for the no. i ([[1]] i=2~N) measuring point. Then, the reliability of the distance data D(i) is determined for a specific number N of measuring points (#14), and OK (reliable) or NG (unreliable) is set for the reliability flag (i) of the distance data corresponding to the no. i measuring point. The luminance near each measuring point is detected (#16), and the luminance data B(i) is determined for the no. i measuring point.

Please delete the paragraph beginning on page 17, line 24 and ending on page 18, line 6 and replace with the following:

B3
lost
If the data of the no. i measuring point are reliable (#20: NO), the reliability of the no. i-1 measuring point is determined (#30). If the data are reliable (#30:

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B3
cont

NO), the routine advances to the previously described #24. If the data are unreliable (#30: YES), the unmeasurable region end point parameter iEnd is set to [i-1] (#32), and the calculation below is executed.
